# Table of contents

*Introduction* .................................................................................................................................................. 6

*Overview* .................................................................................................................................................. 6

*Main Features* ........................................................................................................................................... 7

*The Milpro P4C™ Units* ................................................................................................................................ 8

*The System Main Modes* .......................................................................................................................... 12

  - *Standby* .............................................................................................................................................. 12
  - *Milking* ................................................................................................................................................ 12
  - *Manual Milking* .................................................................................................................................. 14
  - *Rinsing* ............................................................................................................................................... 14
  - *Rinsing Standby* .................................................................................................................................. 15
  - *Sleep Mode* ......................................................................................................................................... 15
  - *Summary of System Modes* .............................................................................................................. 15

*Pushbutton Commands* ............................................................................................................................ 17

*Commands* ............................................................................................................................................... 18

*Pushbutton Commands Table* .................................................................................................................. 21

*System Installation* .................................................................................................................................. 24

*Wiring the Units* ...................................................................................................................................... 30

*Maintenance* ............................................................................................................................................ 35

*Appendices* ............................................................................................................................................. 37

  - *Appendix A - Parameters* ................................................................................................................... 37
  - *Appendix B - Pulsation* ...................................................................................................................... 45
  - *Appendix C – “MC-Remote”, The Palm Software* ............................................................................. 48
  - *Appendix D_1 – Calibration* ................................................................................................................ 54
  - *Appendix D_2 – PULSAMETER 2 Calibration* .................................................................................... 58
  - *Appendix E - Central Rinsing Switch* ................................................................................................... 64
  - *Appendix F1 – MILPRO P4C™* ........................................................................................................... 65
Introduction

Thank you for choosing Milkline's Milpro P4C™ Milking Controller system. This milking management system combines the most up-to-date and sophisticated features with ease of use, and we hope you'll enjoy using it. Please read this guide before starting the installation or operation.

Overview

The Milpro P4C™ is a microprocessor based, integrated control system designed for single milking-point management. It has many new and advanced features including milk yield and flow display, sophisticated pulsation programs with automatic stimulation, flow controlled pulsation, automatic cluster removal, kick-off and low milk alerts, remote-control programming, simple single pushbutton operation, and more.

It controls the milking process from the moment the operator mounts the cups and until the end of the milking process and the milking cluster removal.

The system consists of a small number of highly reliable components, and it is easy to install and operate. The Milpro P4C™ is modular and can be customized to (almost) any requirements. It enables the integration of additional identification and real-time network modules, to create a complete parlor's milking-management system.

The system can be used in parlors of any type including jar systems. The system can be part of Milkline's MilConHM – a complete parlor management system, in this case the Milpro P4C™ serves a milk monitor device and a display for the MilConHM and is connecting on line to PC based system. Additional components such as cow ID readers and tags are also required. The system is designed for simple upgrade and enables gradual investment to suits the farmer needs.
Main Features

° Individual and milk-flow controlled pulsation for each milking point, for short (less then 20%) and efficient milking with minimal irritation to the cow
° A four digit LED display, monitoring milk yield, flow-rate, milking time and portraying milking status and alerts
° A milk flow sensor, based on IR Free Flow Technology, offering reliable and accurate milk-yield monitoring
° Pneumatic pulsation monitoring, including tubes failure and broken liners
° Automatic take-off - The system controls the vacuum operated shutoff valve and the cluster remover (take-off cylinder). The milk flow-rate’s threshold determining detachment is adjustable.
° Kick-off and low milk alerts
° Simple operation using a single pneumatic pushbutton
° A highly flexible remote-control system with 50 different configurable parameters. The parameters can be configured using a Palm PDA with remote-control software
° An option for real-time network capability, enabling integration of MilCon\textsuperscript{HM} - a complete milking management system
The Milpro P4C™ Units

The system is modular, consisting of several modules connected together.

<table>
<thead>
<tr>
<th>Part no.</th>
<th>Name</th>
</tr>
</thead>
<tbody>
<tr>
<td>-</td>
<td>MILPRO P4C™Controller</td>
</tr>
<tr>
<td>0393830M</td>
<td>MASTER EL. PULS. SERVO-PULSE 2 WAY</td>
</tr>
<tr>
<td>0540272</td>
<td>TCR COMPLETE PVC ML DV</td>
</tr>
<tr>
<td>0393760</td>
<td>FFS KIT DX FOR LOW LINE WITH VALVE</td>
</tr>
<tr>
<td>0393762</td>
<td>FFS KIT SX FOR LOW LINE WITH VALVE</td>
</tr>
<tr>
<td>03931983</td>
<td>ELECTRIC START BUTTON (N/C)</td>
</tr>
<tr>
<td>0750142</td>
<td>DF CONNECTION UNIT</td>
</tr>
<tr>
<td>0750145</td>
<td>DF CONNECTION UNIT FOR S/O</td>
</tr>
</tbody>
</table>
Units Description

**MILPRO P4C™ - Controller**
The MILPRO P4C™ is an integrated pulsation and control unit. Inside the unit there is an electronic PCB, consisting of a microprocessor and software that controls the pulsation and milking process. The system has advanced software, which enables sophisticated pulsation schemes including teat-stimulation, milk-flow controlled pulsation, any rate and ratio, changing the take-off flow level and more. The system can be configured using a Palm PDA with special software. (See “MC-Remote”, The Remote Control Software, Appendix C page 57). The MILPRO P4C™ has four digits LED display and flashing LED indicators for milk yield, alerts and other information.

**MASTER EL. PULS. SERVO-PULSE 2 WAY**
The MASTER EL. PULS. SERVO-PULSE 2 WAY is an electronic Master Servo Pulsator 24V.

**TCR COMPLETE PVC ML DV**
The TCR COMPLETE PVC ML DV is a pneumatic cylinder complete of 24V Double valve.

**FFS KIT FOR MILPRO P4C™ DX FOR LOW LINE WITH VALVE**
The FFS Kit includes the FFS30 Free Flow Milk sensor and the pneumatic vacuum valve. The FFS30 belongs to unique and patented Free-Flow milk-flow measuring devices. It measures the milk flow using Near Infrared (NIR) beams. The FFS30 is completely sealed and has no moving parts. The milk flows freely through the sensor inner tube.
Signals indicating flow-rate are sent to the control circuit in the Pulsator where they are processed to provide a wide range of indicators. The FFS30 performs a self-test whenever it is connected to the power supply (also after power supply failure!). Constant blinking of the FFS red light after connection to the power supply when there is no milk flow, indicates a failure of the self-test. In this case the sensor should be replaced. Note that if the system is configured for high line installation the FFS LED will blink with weak signal – This is normal.

**ELECTRIC START BUTTON (N/C)**

This simple and reliable pushbutton is connected to the DF Connection Unit. Simple pressing combinations enable complete control of the system. For an overview and explanation of the available commands see ‘Pushbutton Commands’, page 16.

**DF CONNECTION UNIT FOR MC/MILPRO P4C™/and S/O**

The Connection Card allows for simple wiring of all the units. The card is available also in a ready to install box including water tight glands and a power switch. See ‘Wiring Diagrams’ page 64/65
Operating the System

Note: The Parameters numbers (#) in the text refer to the menu numbers (first column) in the ‘Parameter Table’, appendix A, page 36

Power Up

The system mode after power-up is configurable (parameter #8.1.1) and also depends on the usage of the central rinsing command option. The most common options are:

Fixed Parlor:

- The power-up mode parameter will be set to standby (this is the default). However, if the rinsing command is ON, the system will power-up in rinsing mode and stay in that mode until the central command is turned off.

If the central rinsing command is not in use, the power-up mode will should be set to Rinsing, to ensure proper operation during the automatic rinsing cycle. In this case the operator should bring all the units to standby mode at the beginning the milking by double-press the pushbutton. At the end of the milking the power should be turned off and then turn on again to bring the units to Rinsing Mode.

RTS Systems:

- The Power-up mode should set to Milking.
The System Main Modes

**Standby**

In this mode the system is ready for the next cow or, in case of abnormal removal, ready for resuming milking on the current cow. The pulsation is off, the cluster is removed and the milk-valve closed. There are two standby modes:

- Normal standby mode – The LED indicators are on
- Abnormal standby mode (alert) – The LED indicators blink rapidly and the alert type is displayed

**Milking**

During normal automatic milking, the pulsation is on, the take-off cylinder is down and the shut off valve is open. The LED indication lights are off, and the LED Display shows the milk yield and other data according to the configuration (For a complete summary of LED indications and display options see ‘Display Summary’, page 21). This mode terminates when the milk flow-rate drops below the preset threshold (configurable, see ‘Summary of Pulsation Parameters’ page 44).

**Stages During Milking:**

- **Initial Time** - (parameter #1.1) a set time count starting at the beginning of the milking, designed to prevent early removal. During this time the system will not end the milking regardless of the milk flow. In normal conditions a cow will start giving milk during the Initial Time phase. If after this time the milk flow is still below the threshold (see below), the Secondary Time count will start and the milking will be terminated. If the milk yield was below the minimum (parameter #1.2) a “Low Milk” Alert will be displayed.
In case of reattaching the cluster to the same cow (indicated if attaching is done immediately after take-off, within the time interval defined in parameter #1.6) the initial time will be half of the normal parameter.

° **Normal Milking Termination** - When the milk flow rate goes below the preset threshold (50-1500 gr/min – parameter #1.4) a secondary timer (parameter #1.3) is triggered. At this stage the indication LEDs blink rapidly. At the end of this time, if the flow is still under the threshold and the procedure is not terminated by the operator, (see pushbutton commands), milking is automatically terminated. In the termination process the pulsation stops, the shut-off valve closes and the take-off cylinder is activated. The process comprises of 6 stages. The duration and output of each stage can be controlled individually, enabling for very flexible termination including “liner collapse”, suction of last milk and many other possibilities (see Take-off parameters).

° **Abnormal Milking Termination** (LEDs indication blinks rapidly).

An abnormal termination is defined as one of the following cases:

a. The total yield at the end of the milking is below the minimum (parameter #1.2). In this case the termination procedure will be carried out as usual.

b. The milk flow drops sharply (sensitivity parameter #1.8) to zero after a minimum yield, (parameter #1.5), which indicates that the milking cluster has fallen or slipped. In this case the shutoff valve is closed immediately and after a delay (parameter #1.9) the cluster will be lifted.
° **Stimulation** - This is a special phase during the milking mode.

In this phase, the Pulsator is running in high frequency (300 PPM - configurable). Because of this high frequency, the liners don’t have time to collapse on the teats. This results in vibrations that massage the teats and stimulate the milk letdown. The stimulation can be started and stopped manually (see pushbutton commands, ‘Start stimulation’, page 16), or automatically - if the milk flow did not reach the required minimum within the predefined time. The stimulation will last up to a predefined interval length, or until the milk starts flowing. The stimulation mode starts automatically by default.

*See stimulation parameters in section 3 of the parameter table, page 39.*

**Manual Milking**

This mode is used for milking problematic cows. In this mode, the indication LEDs blink in the pulsation rate, the pulsation works normally, the take-off cylinder is down and the milk valve is open. In this mode the automatic removal is disabled and the mode is terminated only by a pushbutton command.

Automatic stimulation is disabile but manual stimulation is possible if enabled in normal mode.

**Rinsing**

The MILPRO P4C™ has a Rinsing (Cleaning) mode. In this mode the pulsation is active, the take-off cylinder is down and the vacuum (shut-off) valve is open. The system goes to this mode by using a central switch connecting to all units (see ‘Wiring Diagrams’ on page 64). This enables initiating rinsing for the entire parlor with a single command, saving the need of doing it for each milking point manually. A message ‘CLnS’ is displayed indicating that this mode is on. *See ‘LED Numeric Display’ on p. 21.*
There is option to choose that the system will power up in Rinsing Mode (parameter #8.1.1)

**Rinsing Standby**

When applying a double press when the system is in standby mode the system will go to "Rinsing Standby" mode. In this mode the take-off cylinders will go down and enables the operator to mount the cluster on the rinsing jeters. The vacuum valve and the pulsation will be closed to prevent unnecessary vacuum drop. The units will go to Rinsing mode only after applying the central Rinsing Command.

"Rinsing Standby" is indicated by a 'CLnS' message

**Sleep Mode**

This mode exists (from s/w ver. 2059) to simplify installation and keep the system connected to power at all times. If there is no flow in the FFS for 30 minutes, the system is going to Sleep Mode. In this mode the solenoids are all at rest and the power consumption is minimal.

Once the Central Rinsing Switch is set to Milking the system returns to 'Standby Mode' (or to 'Rinsing Standby Mode' depending on parameter #8.2.6). 'Sleep Mode' is indicated by a 'running snake' on the display.

**Summary of System Modes**
<table>
<thead>
<tr>
<th>Mode</th>
<th>Description</th>
<th>Led Indicators</th>
<th>Vacuum</th>
<th>Take off</th>
<th>Pulsation</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>Power Up</td>
<td>Initial Mode</td>
<td>Depend on configuration</td>
<td></td>
<td></td>
</tr>
<tr>
<td>1</td>
<td>Standby</td>
<td>Ready for next cow</td>
<td>On</td>
<td>Off</td>
<td>Up (On)</td>
</tr>
<tr>
<td>1.1</td>
<td>Standby, immediately after milking termination.</td>
<td>Enables continuation of the present cow</td>
<td>On</td>
<td>Off</td>
<td>Up</td>
</tr>
<tr>
<td>1.2</td>
<td>Abnormal milking termination</td>
<td>Goes back to standby</td>
<td>Blinking rapidly</td>
<td>Off</td>
<td>Up</td>
</tr>
<tr>
<td>2</td>
<td>Milking</td>
<td>The milking mode consist of sub modes:</td>
<td>Off</td>
<td></td>
<td></td>
</tr>
<tr>
<td>2.1</td>
<td>Initial delay</td>
<td>At milking start</td>
<td>Off</td>
<td>On</td>
<td>Down</td>
</tr>
<tr>
<td>2.2</td>
<td>Secondary delay</td>
<td>Before take-off</td>
<td>One LED blinking very rapidly</td>
<td>On</td>
<td>Down</td>
</tr>
<tr>
<td>2.3</td>
<td>Milking with manual stimulation</td>
<td>Teat stimulation</td>
<td>Off</td>
<td>On</td>
<td>Down</td>
</tr>
<tr>
<td>2.4</td>
<td>Milking with automatic stimulation</td>
<td>Teat stimulation</td>
<td>Off</td>
<td>On</td>
<td>Down</td>
</tr>
<tr>
<td>3</td>
<td>Rinsing</td>
<td>For Rinsing Cycle</td>
<td>Off</td>
<td>On</td>
<td>Down</td>
</tr>
<tr>
<td>3.1</td>
<td>Rinsing Standby</td>
<td>Rinsing preparation</td>
<td>Off</td>
<td>Off</td>
<td>Down</td>
</tr>
<tr>
<td>3.2</td>
<td>Sleep*</td>
<td>Between shifts</td>
<td>Off</td>
<td>Off</td>
<td>Down</td>
</tr>
<tr>
<td>M</td>
<td>Manual Milking</td>
<td>Auto. Take off and kick-off handling are disabled</td>
<td>Blinking In pulsation rate</td>
<td>On</td>
<td>Down</td>
</tr>
</tbody>
</table>

* available from s/w versions 2059 and up.
Pushbutton Commands

Overview

The Milpro P4C™ is controlled by a single electric pushbutton.

Most of the operations are initiated with a single hit of the pushbutton. For some, less frequent operations, a combination of hits is required. The principle is simple and our experience shows that operators master it very quickly.

Note: If the central rinsing option is used and the central rinsing switch is in rinsing position, the pushbutton will not react.

The Pushbutton operation types are:

- Press the pushbutton once
- Press the pushbutton twice
- Long, continuous pressing of the pushbutton, for at least 2 seconds

The effect of each operation depends on the current system mode in which it is being executed.
Commands

Start Milking
Operation: hitting the pushbutton once.
Result: The cluster remover is released; the shut-off valve is opened (supplying vacuum to the cluster), enabling mounting of the cups.
Effective: in Standby Mode.

Terminate Milking and Rest Alerts (return to Standby mode)
Operation: hitting the pushbutton twice.
Result: This command returns the system to standby mode from almost every mode the system is in at that moment. However -if the system is already in standby mode, hitting the pushbutton twice will initiate milking.
Effective: in all milking and modes and if alert exists.

Change to Manual Mode
Operation: one long continuous press on the pushbutton, for at least 2 seconds
Result: Neutralizes the automatic milking termination. Switching to manual can be done during milking or immediately after it starts. The cluster remover is released and the cups are down or mounted on the cow
Effective: When the system is in standby or automatic mode

Terminate Manual Mode
Operation: one long continuous press on the pushbutton, for at least 2 seconds.
Result: This command reverses the Manual Mode command, and returns the system manual mode to normal (automatic) milking mode.
Effective: When the system is in manual mode.
Start Stimulation

**Operation:** hitting the pushbutton once.

**Result:** Initiates manual stimulation for 30 second.

**Effective:** While in milking or manual modes.

**Note:** This command is rarely used. It is applied when a cow does not give milk and the automatic stimulation is disabled or didn’t affect the cow.

Terminate Stimulation:

**Operation:** hitting the pushbutton once.

**Result:** stops the stimulation and brings the system back to regular milking mode

**Effective:** While in stimulation mode, either manually or automatically initiated.

Commands Summary:

The effect of each command depends on the current system mode in which it is being executed.

**Warning!:** the definition of the commands type (the intervals) was carefully chosen based on our long experience. However, they can be changed by configuring the pushbutton parameters. Please note that any change can result in severe interference with the unit operation.
The effect of the pushbutton commands in various system modes is:

**Single Press:**
- In standby mode - Start milking (automatic milking mode).
- In Milking or Manual Milking modes - Start stimulation
- In Stimulation - Stop stimulation

**Double Press:**
- In Standby mode – Go to Rinsing Standby mode
- In all other modes - Go to Standby mode

**Long Press** (2 seconds):
- In Standby mode - Start Manual milking mode
- In Milking (automatic) mode - Change to Manual (the ACR will be disabled)
- In Manual mode - Shift back to normal (automatic) milking

**Very Long Press** (> 3.5 seconds):

This option is not in use from software version 2059 and onward.

In older versions or if parameter 8.2.6 CONCARD is set to "Old":
- In Standby mode (After both regular and irregular termination)
  - Go to Rinsing mode
- In all other modes – No effect
## Pushbutton Commands Table

*Note: The left column “Status No.” represents the system mode in which the action is taken. All other columns represent the system mode that result from the action specified in the column’s title. The numbers refer to the Status No. in the left column. M = Manual*

<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Standby</td>
<td>2.1</td>
<td>3.1</td>
<td>M</td>
<td>N/A*</td>
</tr>
<tr>
<td>1.1</td>
<td>Initial time after take-off</td>
<td>2</td>
<td>2.1</td>
<td>M</td>
<td>N/A</td>
</tr>
<tr>
<td>1.2</td>
<td>Standby after abnormal termination (Kick-off, Low milk)</td>
<td>2.1</td>
<td>1</td>
<td>M</td>
<td>N/A</td>
</tr>
<tr>
<td>2</td>
<td>Milking sub-modes:</td>
<td>2.3</td>
<td>1</td>
<td>M</td>
<td>N/A</td>
</tr>
<tr>
<td>2.1</td>
<td>Initial delay</td>
<td>2.3</td>
<td>1</td>
<td>M</td>
<td>N/A</td>
</tr>
<tr>
<td>2.2</td>
<td>Secondary delay</td>
<td>2</td>
<td>1</td>
<td>M</td>
<td>N/A</td>
</tr>
<tr>
<td>2.3</td>
<td>Stimulation</td>
<td>2</td>
<td>1</td>
<td>M</td>
<td>N/A</td>
</tr>
<tr>
<td>3</td>
<td>Rinsing</td>
<td>N/A</td>
<td>1*</td>
<td>N/A</td>
<td>N/A</td>
</tr>
<tr>
<td>3.1</td>
<td>Rinsing Standby</td>
<td>N/A</td>
<td>N/A</td>
<td>N/A</td>
<td>N/A</td>
</tr>
<tr>
<td>3.2</td>
<td>Sleep</td>
<td>N/A</td>
<td>N/A</td>
<td>N/A</td>
<td>N/A</td>
</tr>
<tr>
<td>M</td>
<td>Manual Milking</td>
<td>M1</td>
<td>1</td>
<td>2</td>
<td>N/A</td>
</tr>
<tr>
<td>M1</td>
<td>Stimulation (in manual mode)</td>
<td>M</td>
<td>1</td>
<td>2</td>
<td>N/A</td>
</tr>
</tbody>
</table>

*Very Long Press is canceled in s/w ver 2059 and onward. In older versions or if parameter #8.2.6 is set to "Old" and the system is in Standby it will bring it to Rinsing Mode(3).

*Note: When the central rinsing switch is on, the pushbutton is disabled and can’t be used to control the unit.*
LED Numeric Display

After power-up, the system displays “MILKLINE” followed by the software version and then switches to the power-up mode (as defined by parameter #8.1.1) or to rinsing mode if central control is used and the switch is in Rinsing position.

The Data displayed during milking and in Standby mode can be one of the following 8 options (controlled by parameter #5.1)

1. Accumulated milk yield
2. Current flow rate - indicated by “F” on the left.
3. Milk yield and flow rate in alternation of 0.5 second
4. Same as 3 but at the end of the milking the average flow will be presented. Indicated by an “A” on the left
5. Same as 3 but at the end of the milking the peak flow will be presented. Indicated by a “P” on the left
6. Milking time in 0.00 (min. sec) structure indicated by “t” on the left
7. Accumulated milk yield and milking time in alternation of 0.5 second
8. Milking stages - for MILKLINE’s technicians

**Measurement Units** - Kg or pound (and Kg/min or Pound/min for milk flow) can be selected using parameter #5.2.

**Alerts**
Alert messages take over the display and are displayed instead of the regular messages.

In an alert situation, the indication LEDS blink and the milk yield and the alert message alternate every 0.5 seconds.

- **Low Milk** - when the milk yield at the end of the milking is less than the specified minimum (parameter #1.2)
- **Kick-off** - When the cluster is dropped (sensitivity parameter #1.8)

**Note**: If the system is connected to a management system ("MilCon\textsuperscript{HM}\textsuperscript{(R)}"), additional messages are available.
System Installation

Overview

The MILPRO P4C™ is designed for simple and straightforward installation, making it suitable for upgrading existing parlors as well as new installations. The system contains advanced software, providing control over a large variety of parameters by using a remote control device. It enables optimal customization to the parlor’s configuration and the individual user’s needs. Following the instructions detailed in this chapter will assure long-term functioning and full satisfaction.

Installing the system is quite simple. However, careful reading of the following instructions should save time and operational problems.

*Note: The installation should be done by an experienced technician of milking equipment.*

Preparation

Proper planning will assure smooth installation. The preparations should be as follows:

Examining the type of the intended parlor (existing or a new one) to determine the following:

- How the installation will be carried out
- The required accessories
- The required wiring
- The power supply
A meeting should be set up with the farm manager, to explain and discuss the various options, and decide on the best set of parameters. If the parlor is active the installation should be planned so as to minimize the interference with the normal milking routine.

The power supplies, cables, wiring braids, connectors and accessories should be prepared in advance. Special attention must be paid to the location of the Sensor and the Pulsator. See “Important Points to consider” in the next paragraph.
Picture 1 - General layout (Low Line)

Vanguard technology that combines in a unique compact system milk production, automatic teat cup remover and pulsation. The single solution to control milking groups individually. The ideal choice to update your milking parlour at the most advanced and available technology, with the minimum investment costs.

- TCR management
- Big display to allow better information view
- Milking functions control by single electric push button
- Milking phase and alarm display
- Microprocessor-controlled and flow-adjustable removal system
- Different pulsation programs, including teat stimulation and flow-controlled pulsation
- Simple installation in existing parlours
- Quick hook / release on stainless steel bail
- Shorter milking time, more operator comfort
- No more over-milking and teat irritation
- Milking ensured with minimum maintenance requirements
- Conductivity detection by the brand new FFS30 COND optical sensor
- Ready to be updated at Milcon HM, the most advanced real-time milking control and herd management system.
Units Installation

The following is an installation checklist. The steps listed don’t necessarily have to be followed in the order listed.

**MASTER EL. PULS. SERVO-PULSE 2 WAY installation**

- Drill a 19 mm diameter hole in the pipe, and remove any swarf.
- Locate the Pulsator Multi Mount over the hole in the pipe with the flat face to the front
- Place the straps into the holes and pull them through until the buckles are seated in the mount.
- Bend the straps around the pipe and insert the strap end into the bucale.
- While holding the buckle firmly pull the strap through until it is tight.
- Vacuumise the plant and retighten the straps using pliers.
- Cut off excess strap.

- Fit the connecting cable into socket I in the Master Pulsator and connect to the Connection Box (see wiring instructions pag. 64/65).
**TCR COMPLETE PVC ML DV installation**

The TCR complete PVC ML DV must be connected to the vacuum line and to the vacuum valve. The electric wirings must be connected in the Connection Box.
FFS Kit for low line with valve installation

FFS Kit is positioned on the milk pipeline and it is composed by FFS30 Infrared Milkflow Detector (connected into the Connection Box) and pneumatic valve (connected into the TCR Complete PVC ML DV).

Electric Start Button installation

The electric start button is useful to control the system and it should be installed in a place most accessible and convenient for the operator. It is connected into the Connection Box.
Wiring the Units

Important:
Before wiring the units please read the ‘Wiring Instructions’, page 30.

1. Wire the units according to the drawing. Every unit has differently marked cables. All the cables end up in a secured connecting point placed high in a conduit in the upper part of the parlor. The wires should be connected using the connections card.

2. Double-check that the wiring and the installation have been properly carried out, and connect the units to the power by starting the vacuum.

   It is recommended to start by connecting only one milking point to the power and checking that the system functions well. After this first check has been successfully carried out you can connect the entire parlor.

3. Choose the desired set of parameters and load all units (See “MC-Remote”, The Palm Software, Appendix D, page 57)

4. Calibrate the units. (See “Calibration”, Appendix C, page 47)
Wiring the Units

Important:
Before wiring the units please read the ‘Wiring Instructions’, page 30.

1. Wire the units according to the drawing. Every unit has differently marked cables. All the cables end up in a secured connecting point placed high in a conduit in the upper part of the parlor. The wires should be connected using the connections card.

2. Double-check that the wiring and the installation have been properly carried out, and connect the units to the power by starting the vacuum.

   It is recommended to start by connecting only one milking point to the power and checking that the system functions well. After this first check has been successfully carried out you can connect the entire parlor

3. Choose the desired set of parameters and load all units (See “MC-Remote”, The Palm Software, Appendix D, page 57)

4. Calibrate the units. (See “Calibration”, Appendix C, page 47)
Wiring Instructions

We recommend using a special TRADO DUAL 24V power supply (0393579).

**Trafo Dual 24V power supply Diagram**
Connections Card (0750142 – 0750145)

The card enables to connect each cable to a dedicated port and considerably simplifies the wiring requirements. The card can be installed inside a proper box or in a conduit according to the specific installation. The card can be ordered in an IP 56 box with glands and ready to install. See drawing below. The card is suitable for MilCon\textsuperscript{HM} installation as well. (See page xx for connection wirings)


**Power lines**

For optimal performance we recommend keeping the system connected to the power supply at all times. The unit automatically goes in to "Sleep Mode" after Rinsing. (Starting from software version 2059)

**Warning! The Pulsators and Double Valves should not operated with out vacuum for long periods to avoid over hitting of the units.**

We recommend dividing the parlor into groups of 8-10 milking points with separate circuits and separate indication lights and circuit breakers for each group. Each power supply should be designed for 300VA. The common (-) of all the power supply lines should be connected together to enable the rinsing command.

Dividing the parlor in groups as described above helps to avoid big conductors (we recommend using stranded 2.5-4 mm² wires, (14-12 AWG) depending on the total length), as it is easier to maintain, and even in case of failure in one group, other groups will remain unaffected.

We also recommend using continuous conductors and special joints to "drop" the connection for each bail to avoid multiple hops.

In rotary parlors we recommend the installation of the power supplies on the platform.

**Extension Cable for FFS**

The extension cable connects the FFS to the Pulsator in low line installations. The cable should be a control cable with 4 stranded wires of 0.5 mm² (20 AWG).

We recommend the connections with the extension cables to be on the side of the pit in a suitable sealed box (common to all FFSs). The FFS can be ordered with longer cable if needed.
Rinsing Command

To bring all units to Rinsing Mode additional wire is connected to all units. Applying a (+) to this wire causes the units to turn to rinsing mode and applying (-) returns the parlor to Standby Mode. This option enables controlling the rinsing mode of the entire parlor.

*Note:* As it shown in the wiring diagram, the central rinsing switch should connect either(-) to the line or(+) for rinsing. The line should not be left "in the air".

Network cable (for future connectivity to MilCon ™):

The network cable type should be *shielded* twisted-pair, stranded wires of 0.4 mm² (22 AWG) with characteristic impedance of 100 ohm and capacitance of 16 pF per foot. (Standard for RS-485). If the common (-) of all PS are not connected a third wire should be included.
Maintenance

Three Months Unit Maintenance

(In case of heavy dust this procedure may be repeated more frequently)

**FFS30**

The FFS30 doesn't require any maintenance.

**MASTER EL. PULSATOR SERVO-PULSE 2 WAY**

The internal air filter is designed as a secondary filter to ensure that only filtered air reaches the pulsation control solenoids. This ensure maximum reliability under all conditions.

Check the filter material at least once a month or after every 200 hours of operation (more often in dusty conditions), and if it shows any build-up of dirt clean it wash it in warm soapy water. Squeeze it dry before refitting it. If the material shows any sign of degradation replace it with a new filter. Use only filters supplied by MILKLINE Milking Systems and its distributors.

The solenoids are factory sealed units and require no maintenance or servicing. If for any reason a solenoid does not operate correctly, replace it with a new unit. To remove a solenoid, unplug it from the circuit board, then release it from the retaining clips by lifting the end closest to the wires upwards and outwards.

To replace a solenoid, insert the ports into the middle plate, push the solenoid into the retaining clips, and plug the wires into the circuit board. When replacing the lid ensure that the 1 mm diameter air admission hole in the end of the solenoid is unobstructed.

Replace the silicone diaphragm at intervals of 2000 hours of pulsator operation. Have the pulsator serviced by an approved service agent if pulsation graphs indicate leakage through the diaphragm.
TCR COMPLETE PVC ML DV

Monthly Maintenance

Open the bottom side of the cylinder and replace the cord if necessary. Lubricate the internal part of the cylinder with silicon oil.
Appendices

Appendix A - Parameters

The MILPRO P4C™ has nearly 50 different configurable parameters. Configuring is done using a Palm™ PDA with special software. The software enables to create, save, upload and retrieve either predefined complete parameters sets, or change specific parameters.

The parameters are divided into 9 groups, each handling different aspects of the MILPRO P4C™ functionality as follows:

Note: the name in capital letters in the brackets refers to the button in the MC-Remote software, see Appendix C, page 57, and the Parameters tables, appendix A, page 38

1. Milking [MILK] – Milking process control, various delays, flow threshold for removal, abnormal termination conditions control etc.

2. Pulsation [PULS] – Controlled or fixed pulsation, see appendix B, Pulsation, page 44

3. Stimulation [STIM] – teat stimulation control, frequency, duration, operation, etc.

4. Pushbutton Control [BUTT] Pushbutton commands definitions; usually there is no need to adjust these parameters

5. Display [DISP] – Changing the display mode and units

6. Take-Off Settings [TKOFF] – take-off process definitions; usually there is no need to adjust these parameters.
7. Non Milking Statuses [NMLK] – System output definitions for standby and rinsing modes; usually there is no need to adjust these parameters.


9. Special I/O Function [FUN_IO] – Special I/O wire-terminal functionality definitions. These parameters should be changed by the system installer according to the wiring.
### Parameters table 1

<table>
<thead>
<tr>
<th>Menu no.</th>
<th>No.</th>
<th>Name</th>
<th>Description</th>
<th>Units</th>
<th>Values Range</th>
<th>Default</th>
<th>Notes</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>Main</td>
<td><strong>Main</strong></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>I</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>I.1</td>
<td>1</td>
<td>MDURS</td>
<td>Initial interval</td>
<td>Sec</td>
<td>50-300</td>
<td>100</td>
<td>See page 7</td>
</tr>
<tr>
<td>I.2</td>
<td>2</td>
<td>MGRAM</td>
<td>Minimum yield (for low milk alert)</td>
<td>Gram</td>
<td>500 – 10,000</td>
<td>3,500</td>
<td></td>
</tr>
<tr>
<td>I.3</td>
<td>3</td>
<td>FMDRS</td>
<td>Final interval</td>
<td>Sec</td>
<td>5 – 30</td>
<td>12</td>
<td></td>
</tr>
<tr>
<td>I.4</td>
<td>4</td>
<td>FHTCS</td>
<td>Flow threshold for removal</td>
<td>Gram</td>
<td>50 – 1500</td>
<td>350</td>
<td></td>
</tr>
<tr>
<td>I.5</td>
<td>13</td>
<td>MDGRM</td>
<td>Min. yield for drop alert</td>
<td>Gram</td>
<td>0 – 30,000</td>
<td>500</td>
<td></td>
</tr>
<tr>
<td>I.6</td>
<td>31</td>
<td>OFDSC</td>
<td>Interval before reset of last cow data</td>
<td>Sec</td>
<td>0 – 180</td>
<td>5</td>
<td></td>
</tr>
<tr>
<td>I.7</td>
<td>37</td>
<td>VACDY</td>
<td>Delay of opening shut off valve</td>
<td>Sec</td>
<td>0-5</td>
<td>1</td>
<td></td>
</tr>
<tr>
<td>I.8</td>
<td>42</td>
<td>SNDRP</td>
<td>Sensitivity of drop (kick-off) detection</td>
<td></td>
<td>-Quick</td>
<td>Normal</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>-Normal</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>-Slow</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>-Very Slow</td>
<td></td>
<td></td>
</tr>
<tr>
<td>I.9</td>
<td>41</td>
<td>TOVHAN</td>
<td>Delay for take-off in drop (kick-off) event</td>
<td>Sec</td>
<td>0-60, 990,991</td>
<td>15</td>
<td>990 - take off disabled 991- in Lo milk alert the cluster stays up</td>
</tr>
</tbody>
</table>

The parameters menus are common for setting a specific parameter or working an a complete set.
<table>
<thead>
<tr>
<th>Menu no.</th>
<th>No.</th>
<th>Name</th>
<th>Description</th>
<th>Units</th>
<th>Values Range</th>
<th>Default</th>
<th>Notes</th>
</tr>
</thead>
<tbody>
<tr>
<td>2</td>
<td></td>
<td>Pulsation</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>2.1</td>
<td></td>
<td>Flow Controlled</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>2.1.1</td>
<td>19</td>
<td>LF</td>
<td>Low flow</td>
<td>Gr./Min</td>
<td>0-3,000</td>
<td>1,200</td>
<td></td>
</tr>
<tr>
<td>2.1.2</td>
<td>20</td>
<td>HF</td>
<td>High flow</td>
<td>Gr./Min</td>
<td>2,000-10,000</td>
<td>7,500</td>
<td></td>
</tr>
<tr>
<td>2.1.3</td>
<td>16</td>
<td>LFAB</td>
<td>Milking phase at low flow</td>
<td>10 X msec</td>
<td>10-100</td>
<td>60</td>
<td></td>
</tr>
<tr>
<td>2.1.4</td>
<td>15</td>
<td>LFCD</td>
<td>Rest Phase at low flow</td>
<td>10 X msec</td>
<td>10-100</td>
<td>40</td>
<td></td>
</tr>
<tr>
<td>2.1.5</td>
<td>18</td>
<td>HFAB</td>
<td>Milking phase at high flow</td>
<td>10 X msec</td>
<td>10-150</td>
<td>107</td>
<td></td>
</tr>
<tr>
<td>2.1.6</td>
<td>17</td>
<td>HFCD</td>
<td>Rest Phase at high flow</td>
<td>10 X msec</td>
<td>10-100</td>
<td>40</td>
<td></td>
</tr>
<tr>
<td>2.2</td>
<td></td>
<td>Fixed pulsation</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>2.2.1</td>
<td>16</td>
<td>AB</td>
<td>Milking Phase</td>
<td>10 X msec</td>
<td>10-100</td>
<td>60</td>
<td></td>
</tr>
<tr>
<td>2.2.2</td>
<td>15</td>
<td>CD</td>
<td>Rest Phase</td>
<td>10 X msec</td>
<td>10-100</td>
<td>40</td>
<td></td>
</tr>
<tr>
<td>2.2.3</td>
<td>36</td>
<td>PPLB</td>
<td>Reduced Milking for front quarters</td>
<td>%</td>
<td>0-20</td>
<td>0</td>
<td></td>
</tr>
<tr>
<td>2.3</td>
<td></td>
<td>PULSSTY LE</td>
<td>Pulsation Style</td>
<td></td>
<td>1: 2x2</td>
<td>2x2</td>
<td>Software Ver 1029 and above</td>
</tr>
<tr>
<td>3</td>
<td></td>
<td>Stimulation</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>3.1</td>
<td>22</td>
<td>MSGPB</td>
<td>Interval of phase A+B in stimulation</td>
<td>10 X msec</td>
<td>10-15</td>
<td>10</td>
<td></td>
</tr>
<tr>
<td>3.2</td>
<td>21</td>
<td>MSGPD</td>
<td>Interval of phase C+D in stimulation</td>
<td>10 X msec</td>
<td>10-15</td>
<td>10</td>
<td></td>
</tr>
<tr>
<td>3.3</td>
<td>23</td>
<td>MSGMF</td>
<td>Flow limit for auto. Stimulation</td>
<td>Gr./Min</td>
<td>60-1800</td>
<td>1000</td>
<td></td>
</tr>
<tr>
<td>3.4</td>
<td>24</td>
<td>MSGMD</td>
<td>Max. stimulation interval</td>
<td>Sec</td>
<td>10-100</td>
<td>30</td>
<td></td>
</tr>
<tr>
<td>3.5</td>
<td>38</td>
<td>AUTEN</td>
<td>Delay for auto. Stimulation (depends on flow limit)</td>
<td>Sec</td>
<td>0-300</td>
<td>30</td>
<td></td>
</tr>
<tr>
<td>3.6</td>
<td>25</td>
<td>ENMSG</td>
<td>Stimulation status</td>
<td></td>
<td>1: Disabled</td>
<td>Auto</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>2: Manual</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>3: Auto</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>4: Auto+Man</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

|        |     | Pushbutton |                                      |          |               |         |                            |

V277E – 30.03.09  40  Milpro P4C™ Installation and Operation Manual
<table>
<thead>
<tr>
<th>Menu no.</th>
<th>No.</th>
<th>Name</th>
<th>Description</th>
<th>Units</th>
<th>Values Range</th>
<th>Default</th>
<th>Notes</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>control</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>4.1</td>
<td>26</td>
<td>MINSHORT</td>
<td>Lower limit for short press</td>
<td>msec</td>
<td>20-600</td>
<td>40</td>
<td></td>
</tr>
<tr>
<td>4.2</td>
<td>27</td>
<td>MAXSHORT</td>
<td>Upper limit for short press</td>
<td>msec</td>
<td>620-2,000</td>
<td>1,200</td>
<td></td>
</tr>
<tr>
<td>4.3</td>
<td>28</td>
<td>MAXLONG</td>
<td>Max interval for long press</td>
<td>msec</td>
<td>2,010-4,000</td>
<td>3,500</td>
<td></td>
</tr>
<tr>
<td>4.4</td>
<td>29</td>
<td>MINOF</td>
<td>Min. interval between two presses for double press</td>
<td>msec</td>
<td>20-600</td>
<td>40</td>
<td></td>
</tr>
<tr>
<td>4.5</td>
<td>30</td>
<td>MAXOF</td>
<td>Max. interval between two presses for double press</td>
<td>msec</td>
<td>620-2,000</td>
<td>700</td>
<td></td>
</tr>
<tr>
<td>5</td>
<td></td>
<td>Display</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>5.1</td>
<td>34</td>
<td>DDMODE</td>
<td>Display mode</td>
<td></td>
<td>See table 2 on page 58</td>
<td>Yield</td>
<td></td>
</tr>
<tr>
<td>5.2</td>
<td>35</td>
<td>DISPUNIT</td>
<td>Measuring units</td>
<td>Kg, Pounds</td>
<td>Kg</td>
<td></td>
<td></td>
</tr>
<tr>
<td>6</td>
<td>5-10</td>
<td>Take Off Setting</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>7</td>
<td></td>
<td>Non Milking Statuses</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>7.1</td>
<td>11</td>
<td>NMILKSET</td>
<td>System status in standby mode</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>7.2</td>
<td>12</td>
<td>CLENSET</td>
<td>System status in Rinsing mode</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>8</td>
<td></td>
<td>General</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>8.1</td>
<td></td>
<td>Power up</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>8.1.1</td>
<td>39</td>
<td>PWR_UP</td>
<td>System Status at power up</td>
<td></td>
<td>1: Manual 2: Rinsing 3: Standby 4: Milking*</td>
<td>Standby</td>
<td>*software Ver 1029 and above</td>
</tr>
<tr>
<td>8.1.2</td>
<td>40</td>
<td>VV_DLY</td>
<td>Delay for opening the shutoff valve at power up</td>
<td>Sec</td>
<td>0-300</td>
<td>0</td>
<td>Needed if vacuum reserve is low</td>
</tr>
<tr>
<td>8.2</td>
<td></td>
<td>System setup</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>8.2.1</td>
<td>43</td>
<td>BIAS</td>
<td>Set constant correction to sensor input</td>
<td></td>
<td>600-1500</td>
<td>1000</td>
<td>See App. C page 63</td>
</tr>
<tr>
<td>Menu no.</td>
<td>No.</td>
<td>Name</td>
<td>Description</td>
<td>Units</td>
<td>Values Range</td>
<td>Default</td>
<td>Notes</td>
</tr>
<tr>
<td>----------</td>
<td>-----</td>
<td>------------</td>
<td>-----------------------------------------------</td>
<td>----------------------------</td>
<td>-------------------------------------------------</td>
<td>----------------------------------------------</td>
<td>---------------------------------</td>
</tr>
<tr>
<td>8.2.2</td>
<td>48</td>
<td>SENSOR</td>
<td>Define type of sensor installation</td>
<td></td>
<td>1: High Line  2: Low Line</td>
<td>New Protocol Lo line installation</td>
<td>** See Note below</td>
</tr>
<tr>
<td>8.2.3</td>
<td>49</td>
<td>SHOFFT</td>
<td>Define the Shot-off valve type</td>
<td></td>
<td>1: Diaphragm  2: Clamp</td>
<td>Clamp</td>
<td>Ver 1026 and above</td>
</tr>
<tr>
<td>8.2.4</td>
<td>50</td>
<td>ACRMODE</td>
<td>ACR mode</td>
<td></td>
<td>1: Take-Off Cylinder  2: Pulsation Arrest</td>
<td>Take-Off Cylinder</td>
<td>Ver 1029 and above</td>
</tr>
<tr>
<td>8.2.5</td>
<td>59</td>
<td>ADDRESS</td>
<td>Node Address</td>
<td></td>
<td></td>
<td>MiCon &amp; special applications</td>
<td></td>
</tr>
<tr>
<td>8.2.6</td>
<td>60</td>
<td>SLEEP</td>
<td>Sleep Mode Style</td>
<td></td>
<td>1: Old  2: Wake up in 'Standby Mode'  3: Wake up in 'Rinsing Standby Mode'</td>
<td>Wake up in 'Standby Mode'</td>
<td>See page 73 for more info</td>
</tr>
<tr>
<td>8.2.7</td>
<td>65</td>
<td>REMROT</td>
<td>Functionality of rotary remote control</td>
<td></td>
<td>1: enable reset while milking  2: Disable reset while milking</td>
<td>1: enable reset while milking</td>
<td>Rotary fixed remote control</td>
</tr>
<tr>
<td>8.3</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>MiCon</td>
<td></td>
</tr>
<tr>
<td>8.3.1</td>
<td>61</td>
<td>IDENT</td>
<td>Type of ID</td>
<td></td>
<td></td>
<td>MiCon</td>
<td></td>
</tr>
<tr>
<td>8.3.2</td>
<td>62</td>
<td>PARLOR</td>
<td>Parlor Type</td>
<td></td>
<td></td>
<td>MiCon</td>
<td></td>
</tr>
<tr>
<td>9</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>MiCon</td>
<td></td>
</tr>
<tr>
<td>9.1</td>
<td>46</td>
<td>IN/Rinse</td>
<td>Active only if param 8.2.6 is in Old</td>
<td></td>
<td>1: Single Press  2: Conditional</td>
<td>2: Conditional</td>
<td>In Ver 2059 and above</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>In old mode</td>
</tr>
<tr>
<td>9.2</td>
<td>47</td>
<td>OUTPUT</td>
<td>Currently not in use</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>9.3</td>
<td>63</td>
<td>DRPDLY</td>
<td>A special function for lowering the cluster during milking for back-flush</td>
<td>Sec</td>
<td>5-120</td>
<td>10</td>
<td>Use with special device for rinsing between gangs</td>
</tr>
</tbody>
</table>
Warning! The Parameters in tables 2 and 3 have complicated effects and should be changed only by an expert with full understanding of the system.

Parameters Table 2

Display Modes (5.1 in Table 1)

<table>
<thead>
<tr>
<th>Display Mode</th>
<th>Default</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 Yield Only</td>
<td>X</td>
</tr>
<tr>
<td>2 Flow Only</td>
<td></td>
</tr>
<tr>
<td>3 Yield &amp; Flow</td>
<td></td>
</tr>
<tr>
<td>4 Yield &amp; Flow / Average Flow</td>
<td></td>
</tr>
<tr>
<td>5 Yield &amp; Flow / Peak Flow</td>
<td></td>
</tr>
<tr>
<td>6 Milking Time</td>
<td></td>
</tr>
<tr>
<td>7 Yield &amp; Milking Time</td>
<td></td>
</tr>
<tr>
<td>8 Milking Stages - Service Only</td>
<td></td>
</tr>
</tbody>
</table>

**Note:** If the system if configured for high line installation the (parameter 8.2.2) the FFS LED will blink constantly with faint signal after the power up self test.

The Take-off process consists of 6 consecutive stages (0 to 5). The duration and the state of each output (valves and signal lights) can be set separately for each stage. As a result the process is highly flexible and can be adjusted to any requirement. The default set enables smooth take-off with last milk sweeping. In most cases these values should not be changed. In a similar way the outputs can be set for Standby and Rinsing modes for special cases.
### Parameters Table 3

#### Menu 6: Take-off Stages

<table>
<thead>
<tr>
<th>Stage</th>
<th>No.</th>
<th>L2</th>
<th>L1</th>
<th>TOV</th>
<th>VV</th>
<th>Pv2</th>
<th>Pv1</th>
<th>Duration 100X msec</th>
<th>Range</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>5</td>
<td>O n</td>
<td>O n</td>
<td>Off</td>
<td>Off</td>
<td>On</td>
<td>On</td>
<td>30</td>
<td>0-128</td>
</tr>
<tr>
<td>1</td>
<td>6</td>
<td>O n</td>
<td>O n</td>
<td>On</td>
<td>Off</td>
<td>On</td>
<td>On</td>
<td>50</td>
<td>0-128</td>
</tr>
<tr>
<td>2</td>
<td>7</td>
<td>O n</td>
<td>O n</td>
<td>On</td>
<td>On</td>
<td>Off</td>
<td>Off</td>
<td>10</td>
<td>0-128</td>
</tr>
<tr>
<td>3</td>
<td>8</td>
<td>O n</td>
<td>O n</td>
<td>On</td>
<td>Off</td>
<td>Off</td>
<td>Off</td>
<td>10</td>
<td>0-128</td>
</tr>
<tr>
<td>4</td>
<td>9</td>
<td>O n</td>
<td>O n</td>
<td>On</td>
<td>Off</td>
<td>Off</td>
<td>Off</td>
<td>0</td>
<td>0-128</td>
</tr>
<tr>
<td>5</td>
<td>10</td>
<td>O n</td>
<td>O n</td>
<td>On</td>
<td>Off</td>
<td>Off</td>
<td>Off</td>
<td>0</td>
<td>0-128</td>
</tr>
</tbody>
</table>

#### Menu 7: Non milking modes

<table>
<thead>
<tr>
<th>7.1 - Standby</th>
<th>12</th>
<th>Off</th>
<th>Off</th>
<th>On</th>
<th>Off</th>
<th>Off</th>
<th>Off</th>
</tr>
</thead>
<tbody>
<tr>
<td>7.2 - Rinsing</td>
<td>11</td>
<td>Off</td>
<td>Off</td>
<td>On</td>
<td>Pul</td>
<td>Pul</td>
<td>Pul</td>
</tr>
</tbody>
</table>

**Key:**
- L1, L2 – Signal LEDs
- TOV – Take-Off Valve
- VV – Vacuum (Shut-Off) Valve
- PV1, PV2 – Pulsation Valves
Appendix B - Pulsation

The pulsation parameters define the milking phase (A+B) and the rest phase (C+D). The phase duration values are given in 10\(^{th}\) of millisecond. In the following table we show few common settings that will help you understand the translation to rate and ratio:

<table>
<thead>
<tr>
<th>No.</th>
<th>Rate PPM</th>
<th>Ratio %</th>
<th>Milking phase A+B (10(^{th}) msec.)</th>
<th>Rest phase C+D (10(^{th}) msec.)</th>
</tr>
</thead>
<tbody>
<tr>
<td>60</td>
<td>60:40</td>
<td>60</td>
<td>60</td>
<td>40</td>
</tr>
<tr>
<td>55</td>
<td>60:40</td>
<td>65</td>
<td>44</td>
<td></td>
</tr>
<tr>
<td>60</td>
<td>65:35</td>
<td>65</td>
<td>35</td>
<td></td>
</tr>
<tr>
<td>60</td>
<td>70:30</td>
<td>70</td>
<td>30</td>
<td></td>
</tr>
</tbody>
</table>

The MILPRO P4C™ has two pulsation modes:

Flow-controlled pulsation
Fixed pulsation.

Flow-Controlled Pulsation (default)

In this pulsation method, the pulses are changing dynamically during the milking, reacting to the milk flow. As the flow increases the pulsation’s milking phase (A+B) becomes longer, while the rest phase (C+D) remains constant. As a result, the pulsation rate slows down. This performance is achieved because the FFS is monitoring the flow online and in real time, unlike other systems where the flow monitoring is very limited.

The idea behind the controlled pulsation is that high production cows can benefit from milking in longer strokes since the duct system and the teat cisterns in the udder are larger. The benefits are faster milking (up to 20\% reduction in milking time), less teat irritation, and less liners.
wearing. The method is also very safe because if, for whatever reason, the cow is uncomfortable with longer strokes the flow rate will decrease and the pulsation will immediately change back to the initial values.

The controlled pulsation 6 parameters are:

1. Low flow rate - the flow level in which the pulsation starts changing (Parameter #2.1.1)
2. Milking phase (A+B) in low flow rate (Parameter #2.1.3)
3. Rest phase (C+D) in low flow rate (Parameter #2.1.4)
4. High flow rate – the flow level in which the pulsation stops changing (Parameter #2.1.2)
5. Milking phase (A+B) in high flow rate (Parameter #2.1.5)
6. Rest phase (C+D) in high flow rate (Parameter #2.1.6)

Parameters 1 & 2 above determine the initial pulsation (in milliseconds – see the table below). The pulsation stays constant as long as the flow is below the low flow-rate (1). Between the low flow level and the high flow level (4) (the dynamic area) the pulsation will change in accordance with the flow.

When the milk flow is above the high flow-level, the pulsation will be constant according to parameters 5 & 6.

We recommend using default setting. These settings are the result of 10 years of field experience in Israel and Europe. After gaining some experience with the system, the parameters can be changed based on your own field experience.

Customers are most welcome to send us comments and feedback on the system performance.
Fixed Pulsation

If you choose to use fixed pulsation you only need to change two parameters - the milking phase (#2.2.1) and the rest phase (#2.2.2).

Note: Parameters 2.2.1 and 2.2.2 control the initial pulsation if controlled pulsation is used, and also the fixed pulsation and the pulsation during rinsing.
Appendix C – “MC-Remote”, The Palm Software

Overview

The MILPRO P4C™ is configured by an infrared remote control similar to that of a TV set. By installing the MC-Remote software on a Palm PDA it is easy to control all the MILPRO P4C™ features. This chapter deals with installing and using the palm software.

For details and description of the different configurable parameters see the parameters table on page 38

Specifications

Device*: Palm -Vx, m130,m505, m515, Zire (m150), TUNGSTEN E/T, Sony - CLIE SJ10, CLIE SJ22

Software version*: PALM OS 3.5, 4.1, 5.2.1

*Different Devices and OS require different files - see README.TXT in the MC_Remote files set.

Modules

1. Remote.prc - IR controller.

2. MC_Remote.prc - The configuration software.
Installing and Registering the Software

The modules are installed from a PC like any other Palm software, using the “Palm Desktop”.

1. Make sure that the Palm Desktop Software is properly installed on your PC and connect the PDA to the PC.

2. Double click on the files Remote.prc ORLibxxx.prc (xxx represents the file version according to the device and OS in use) and MC_Remote-vyyyy.prc (yyyy represent the file version) supplied by MILKLINE.

3. The Palm’s “Install Tool” Dialog box will appear after the first click and both files will be added to the list of files in the box. Press “Done” and then “OK”

4. Synchronize your Palm by pressing the “HotSync” button on the docking station. The Icons of both modules should appear on your Palm’s main menu.

5. Send your user name to the palm (click the HotSync icon - the name is written in the right upper corner of the screen)

6. Send the user name to sales@milkline.com and we will send you a registration code for the Remote.prc module

7. After you received the code, click the ‘Remote Icon’, click on the ‘OmniRemote Pro’ label at the upper right corner, choose ‘Option’ then ‘Registration’ and insert the code

As a bonus you can train the palm to act as a TV remote control – see the Remote Module.
Using the Software

The MC-Remote is a simple, menu-based program that enables you to do the following:

- Retrieve and save the parameters-set from the MILPRO P4C™ on the Palm
- Edit a parameter set
- Load a parameter set to the MILPRO P4C™
- Retrieve, change, and load any single parameter

Like any other IR device, in order to communicate the Palm topside should point to the direction of the MILPRO P4C™ front panel.

A successful transmitting will be indicated by a bleep in the palm and by a short “Done” message on the MILPRO P4C™ display.

After clicking on the MC-Remote Icon, a two items menu will appear:

![Picture 1 - Top Menu](image)

The PARAMS button enables you to browse through all the parameters and retrieve, change, and load any of them.

The Parameters are divided into 9 submenus, each handling a different functionality.
There are two types of parameters:

1. **Open parameters** - Theses are parameters with a value that can be freely entered. They can be handled individually or as part of a parameters set.
   
   a. When handled individually the value can either be written (or keyed) in, or retrieved from the MILPRO P4C™. The updated value can then be uploaded to the MILPRO P4C™ using the ‘transmit’ button.
   
   b. When handled as part of a parameters set the parameter value can be freely entered and saved but only the set can be retrieved and uploaded to the MILPRO P4C™.

2. **Closed-set parameters** - Theses are parameters with a predefined set of values.

   a. In single parameter mode, once you select the parameter the software will automatically try to read the current value from the pulsator – so make sure you hold the Palm facing the unit you want to
update. After selecting the desired value, pressing the ‘Done’ button will automatically load the setting to the unit.

b. In Sets mode the selection can be changed and saved by pressing the ‘Done’ button. Use the ‘Esc’ button to leave the setting unchanged.

Warning! While the MILPRO P4C™ is very flexible and can be adapted to various conditions, some of the parameters are less likely to be changed and some can disrupt the proper system operation if carelessly changed. For those parameters an additional password is required.

To work on a whole set choose SETS.

After choosing SETS you can either choose any set that was previously saved or retrieve a complete set from the MILPRO P4C™. After retrieving a set you can change it and reload it to the MILPRO P4C™.

The menus for changing a single parameter or working on a set are similar. A message at the lower half of the screen will indicate the mode of operation.

Help

Clicking on the HELP button at each submenu will present a list of descriptions of all the parameters belonging to that submenu.
Common Tasks

Configuring the MILPRO P4C™ in a new installation

After deciding on the desired configuration, go to SETS, choose READ_F, Pick the set which is nearest to your needs, save it under a new name using SAVE_AS, change all the parameters that need to be changed, save it using SAVE, and then load it to the first MILPRO P4C™. Check that the milking point is functioning well, make adjustments and then load the same set to all the other units.

Changing a single parameter

Go to PARAMS, browse in the menus for the required parameter. If the parameter has a close set of options to choose from the software will automatically try to retrieve the current setting. If the value is numeric then the current value can be retrieved from the MILPRO P4C™ by using the READ button in the parameter screen. After changing the parameter, load it back to the MILPRO P4C™ using the TRANSMIT button.

To make sure that the configuration is identical in all units in case that more then one parameter was changed, it is recommended to retrieve the updated set from the first unit, save it under a new and meaningful name (our advise is to include the date) and then load the complete set to the rest of the units.
Appendix D_1 – Calibration

In order to achieve optimal accuracy, the MILPRO P4C™ (like any other measuring device) requires initial calibration. The calibration is needed to adjust the MILPRO P4C™ for the special conditions of a specific parlor.

The calibration does not influence the basic accuracy of the MILPRO P4C™ but it can correct a “shift” (called bias) in the measurements that can occur due to specific conditions.

Since the MILPRO P4C™ is very stable, calibration is needed only once after installation and from that point on the MILPRO P4C™ will be accurate as long as the parlor remains the same and no changes were made on the installation or milking equipment. We will demonstrate two ways to perform the calibration, by using the total milk in the tank and individual calibration.

Prior to calibration check the parlor for normal and standard milking conditions:
- Normal vacuum levels (44 ± 2 kPa for low line and 48 ± 2 kPa for High line)
- All clusters in good shape (bleeder, liners, tubes etc…)

Calibration Using the Milk Tank (Vat)

This method is relatively simple and does not require any equipment. In most cases this option is sufficient for achieving good results.

Requirements:

° Accurate scale in the milk tank.

° Palm with MC-remote software
**Procedure:**

1. Write down the amount of milk in the tank.
2. Start the milking.
3. Write down the milk yield of each cow as it appears on the MILPRO P4C™ display.

4. At the end of the milking calculate the average bias:
   a. Write down the exact volume of milk in the tank.
   b. Calculate the net amount of milk for this milking by subtract the volume in the tank at the beginning of the milking, add milk that was taken to feed calves etc...
   c. Convert the total volume to weight (kg) by multiply the volume by 1.032 (denote -Yt).
   d. Sum the yield of all the cows as they appear on the MILPRO P4C™ (denote -YM)
   e. Calculate the average bias for the parlor:

   \[ \text{Bias} = \frac{Y_t}{Y_m} \times 1000 \]

5. Adjust the bias of all units using the Palm.
6. Save the new bias in the parameters set for this parlor.

**Example:**

If the amount of milk in the tank is 540.2 liter and 20 liters of milk was taken to feed calves, and the calculated sum of all the yields of all the cows is 590.6 kg then the bias is:

\[ Y_m = 590.6 \text{ kg} \]
\[ Y_t = (540.2 + 20) \text{ liter} \times 1.032 \text{ kg/liter} = 578.12 \text{ kg} \]

\[ \text{Bias} = \frac{Y_t}{Y_m} \times 1000 = \frac{578.12}{590.6} \times 1000 = 979 \text{ (rounded)} \]

This bias should be updated in the Palm on the parameter file for that parlor and transmitted to all units in the parlor.
Individual Calibration

In this method the calibration is done individually for each milking point, which is more accurate but requires more work.

Required accessories:

- One or more 30 liter vacuum buckets for collecting the milk.
- Accurate (± 10 gr) scale to weight the milk bucket/s
- Palm with Mc-Remote software

In this method every unit is calibrated individually.

Procedure:

1. choose a milking point, connect the collecting bucket and milk 6-8 different cows (if the results are similar i.e. the tendency of the bias is the same then 4 cows maybe enough) , make sure that the milking is normal and finished in a normal way. Write down the yield of each cow as it appears on the display at the end of the milking together with the true yield form the scale (remember to reset the scale with the bucket !!!)

2. Calculate the Bias:
   a. Sum all of the yields from the MILPRO P4C™ and disregards yields of abnormal cows (colostrums, Mastitis low yield, manual milking etc..) (Ym).
   b. Sum all the yields from the scale for the same cows. (Yt)
   c. Calculate the bias same way as explained above (See 1.4).
      
      \[ \text{Bias} = \frac{Yt}{Ym} \times 1000 \]

3. Adjust the unit bias by using the Palm.

4. Repeat steps 1 to 3 for all milking points in the parlor.
**Example (Individual Calibration):**

Milking point No. 1

<table>
<thead>
<tr>
<th>No.</th>
<th>Cow</th>
<th>MILPRO P4C™ (Ym)</th>
<th>Scale (Yt)</th>
<th>Remark</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>101</td>
<td>11.2</td>
<td>11.6</td>
<td></td>
</tr>
<tr>
<td>2</td>
<td>80</td>
<td>9.4</td>
<td>8.7</td>
<td></td>
</tr>
<tr>
<td>3</td>
<td>69</td>
<td>8.3</td>
<td>8.3</td>
<td></td>
</tr>
<tr>
<td>4</td>
<td>125</td>
<td>13.2</td>
<td>14.1</td>
<td></td>
</tr>
<tr>
<td>5</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>6</td>
<td>93</td>
<td>3.2</td>
<td>3.1</td>
<td>Mastitis</td>
</tr>
<tr>
<td>7</td>
<td>44</td>
<td>10.6</td>
<td>11.0</td>
<td></td>
</tr>
</tbody>
</table>

* Total* | Ym 64,70 | Yt = 65,5

* Disregard result No. 6 since it is a sick cow.

**Bias = 65.5 / 64.7 * 1000 = 1012** (Rounded)
Appendix D_2 – PULSAMETER 2 Calibration

The system is pre-set with factory parameters to work immediately but after the installation at the milking positions, an adjustment to each milking point has to be carried out by a fine calibration procedure.

At the Start Up of the system

When the milking system is put into operation the first time or when a milkmeter of the system is exchanged, the calibration value of ‘100’ is set as default. A fine calibration is to be done four weeks after the first start up. The fine calibration procedure have to be carried out according to the following points of these instructions. At the first calibration procedure as well as at routine checks, always qualified personnel are to be consulted, in order to remedy distinguishable deficiencies.

Required equipment for the Calibration Procedure.

The followings tolls have to be selected in order to perform the calibration procedure:

- a suitable milk can,
- a scale with 10 g of resolution,
- a standardized intake tube with concave intake nozzle (3 kg/min) and air nozzle (8-10 l/min),
- a bucket of at least 10 kg capacity,
- a thermometer.
**The Set Up for the Calibration Procedure**

The followings tasks have to be made in order to correctly set up the calibration procedure:

- the bucket is to be filled with water with a temperature of ca. 30 °C and is to be put on the platform of the cow,
- the long milk tube of the milking unit is to be taken off from the inlet connections and the standardized intake tube of the test unit is to be attached on these connections,
- before every measuring the tipping scale is to be emptied by operating the two air inlet plates on the top of the milkmeter,
- the end of the tube with intake nozzle is to be dipped down to the bottom of the bucket. The concave end of the intake nozzle avoids that the nozzle adheres at the bottom of the bucket,
- when the system start the milking, the water is to be sucked off out of the bucket. The suction nozzle must not suck air and must not be blocked,
- stop the milking when the bucket contains a quantity of 10 ± 0,2 kg.
The Calibration Procedure

The followings tasks have to be made before perform the calibration procedure:

- at least two measurings have to be carried out according to the section 4.3 of this document,
- if the bucket contains 10.0 Kg. and the displayed values are 10.0 ± 0.2 kg, the previous calibration parameter or the default value in case of a new system, can remains unchanged and no further measurement is necessary,
- If the displayed values exceed these limits, a calibration procedure to correct these errors is necessary.

Examples:

1. First measuring: Display = 9,9 kg
2. Second Measuring: Display = 10,0 kg
   ➢ Calibration Parameter: o.k.

Or

3. First measuring: Display = 9,7 kg
4. Second Measuring: Display = 9,8 kg
   ➢ Calibration Parameter: the calibration procedure have to be performed.

The followings tasks have to be made in order to perform the calibration procedure:

- start the milking according to the section 4.3 of this document,
- stop the milking when the bucket contains a quantity around 10 kg,
• record the value on the display. The value on the display can only be taken after the stop of the milking. That is because the milkmeter automatically adds 51 grams (the half of the tipping device) to the recorded quantity of milk when the pushbutton is pushed twice and the LED indication lights remain on.

• Record the weight of the water inside the bucket measured by the balance,

• calculate the Calibrated Volume by the following formula:

  \[
  \text{Calibrated Volume} = \left( \frac{\text{balance}}{\text{milkmeter}} \right) \times 100
  \]

• Repeat the previous tasks at least three times to collect three correct measurings. A measuring is considered to be correct if its value compared to the average value of the other measurings is less than 2%.

• Calculate the Calibration Parameter as the average value of the tree correct measurings collected

**Example 1:**

<table>
<thead>
<tr>
<th>Display</th>
<th>Balance</th>
<th>Difference (in litres)</th>
<th>Corrected Volume</th>
</tr>
</thead>
<tbody>
<tr>
<td>10.5</td>
<td>10.83</td>
<td>-0.33</td>
<td>103.14</td>
</tr>
<tr>
<td>10.9</td>
<td>11.24</td>
<td>-0.34</td>
<td>103.12</td>
</tr>
<tr>
<td>10.8</td>
<td>11.11</td>
<td>-0.31</td>
<td>102.87</td>
</tr>
</tbody>
</table>

➢ On the basis of these results the average value is determined as following:

➢ \((103.14 + 103.12 + 102.87)/3 = 103.04\)

➢ and the Calibration Parameter can be set to 103.
**Example 2:**

<table>
<thead>
<tr>
<th>Display</th>
<th>Balance</th>
<th>Difference (in litres)</th>
<th>Corrected Volume</th>
</tr>
</thead>
<tbody>
<tr>
<td>10.8</td>
<td>9.92</td>
<td>0.88</td>
<td>91.85</td>
</tr>
<tr>
<td>10.8</td>
<td>10.51</td>
<td>0.29</td>
<td>97.31</td>
</tr>
<tr>
<td>10.7</td>
<td>10.39</td>
<td>0.31</td>
<td>97.10</td>
</tr>
</tbody>
</table>

➢ In this example the average value of the first three measurements is 95.42. The measurements may deviate 2% from this average (i.e. from 93.51 to 97.33) so that the first measuring is not correct and a fourth measuring is necessary in order to figure out the Calibration Parameter.

**Example 2b:**

<table>
<thead>
<tr>
<th>Display</th>
<th>Balance</th>
<th>Difference (in litres)</th>
<th>Corrected Volume</th>
</tr>
</thead>
<tbody>
<tr>
<td>10.8</td>
<td>9.92</td>
<td>0.88</td>
<td>91.85</td>
</tr>
<tr>
<td>10.8</td>
<td>10.51</td>
<td>0.29</td>
<td>97.31</td>
</tr>
<tr>
<td>10.7</td>
<td>10.39</td>
<td>0.31</td>
<td>97.10</td>
</tr>
<tr>
<td>10.5</td>
<td>10.10</td>
<td>0.40</td>
<td>96.19</td>
</tr>
</tbody>
</table>

➢ On the basis of these four results the average value is determined as following: \( \frac{91.85 + 97.31 + 97.10 + 96.19}{4} = 95.61 \)

➢ and the Calibration Parameter can be set to 96.

➢ Please note that if an extreme measurement is found during the determination of the volume (e.g. a volume of 101 in the above mentioned example), this measurement must not be taken into account when calculating the average in order to prevent that one measurement has too much influence on the average value.

To complete the calibration procedure, the Calibration Parameter have to be stored in the Milpro P4C™ microcomputer. This operation can be done using a Palm™ PDA with a special software. The software enables to create, save,
upload and retrieve either predefined complete parameters sets, or change specific parameters.

In details, the storing of the Calibration Parameter in done by the following steps:

- Start the software application on the PDA,
- select “Sets”,
- read the setting data from the Milpro P4C™ by its IR port selecting the button “Read_P”,
- in the “Param Menu”, select: “GNRL”,
- insert the authorization password: SCR,
- in the “General Menu”, select “MEL”,
- insert the authorization password: milkline,
- in the “Mel Menu”, select “H_PAS”,
- the default or previous value is displayed. Update it with the Calibration Parameter evaluated and select “Ok”,
- select “Esc” until came back to the “Param Menu”,
- select “Save” to store in the PDA the last set of parameters,
- select “Trans” to transfer to the Milpro P4C™ the correct set of parameter by its IR port,
- select “Esc” until quit the application.

Afterwards, a new test for checking the updated system have to be carried out following the tasks explained in the start of this section. If these measurings are within the range of tolerance, the calibration procedure is completed.
Appendix E - Central Rinsing Switch

The central rinsing switch can be operated manually or automatically by the rinsing unit. When the switch is in Rinsing position on the units receive +24V in the I/O function input which bring them immediately to Rinsing Mode. The units will display “CLn”

In order to enable preparation of the parlor for rinsing as quickly as possible we added a special mode “Rinsing Standby” in which the clusters are lowered but the vacuum is closed and the pulsation is arrested in order to keep the vacuum level stable for the cows which are still in milking. This enables to prepare the empty milking points while other milking points are still in milking.

To go to Rinsing Standby a double press should applied when the unit is in standby mode. The Unit then displays “CLnS”

It is also possible manage without the central command (although it is not recommended). In such case the units should be set to start up in Rinsing Mode. In that case the main power should be switched before Rinsing to bring all the units to Rinsing mode.

Note: in old versions (software version lower then 2059) or if parameter 8.2.6 CONCARD is set to ‘Old” - the functionality is different.
Appendix F1 – MILPRO P4C™

Double Valve cylinder

MILPRO P4C

Push button
Washing Box
Master pulsator
Free Flow sensor
Appendix F2 – MILPRO P4C™ + PULSAMETER 2

Double Valve cylinder

MILPRO P4C

Push Button
Washing box
Master pulsator
1 valve Box
Mel 1000
GENERAL PLUGBOARD CHART
FOR MAX 10 MILPRO P4C+ Pulsameter 2

TRAFO1

CONNECTION BOX

1
2
10

WASHING BOX

TRAFO2

EARTH

EARTH

1
2
3
4
5
6
1
2
3
4
5
6

EARTH

EARTH

1
2
3
4
5
6

GENERAL PLUGBOARD CHART
FOR MAX 20 MILPRO P4C+ Pulsameter 2

TRAFO1

CONNECTION BOX

1
2
10

WASHING BOX

TRAFO2

EARTH

EARTH

1
2
3
4
5
6
1
2
3
4
5
6
1
2
3
4
5
6

EARTH

EARTH

1
2
3
4
5
6
1
2
3
4
5
6

EARTH

EARTH

1
2
3
4
5
6
Appendix H – Spare parts

Solenoid 0393065

0540290
0540295

0393070
0540310
0540315

0540325

Piston assembly COD. 0540236

Bayonet insert assy COD. 0540236

Ram cord COD. 0540242

Cluster clip COD. 0540210

COD. 0393830M
MASTER EL. PULS. SERVO-PULSE

COD. 0393830M
TCR COMPLETE PVC ML DV
0540610 Vacuum valve

<p>| | |</p>
<table>
<thead>
<tr>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>0540614</td>
</tr>
<tr>
<td>2</td>
<td>0540616</td>
</tr>
<tr>
<td>3</td>
<td>0540602</td>
</tr>
</tbody>
</table>
I-AL4535 PULSAMETER 2

<p>| | | | | |</p>
<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>2</td>
<td>I-GL4605</td>
<td>12</td>
<td>I-GL4624</td>
<td>25</td>
</tr>
<tr>
<td>3</td>
<td>I-GL4608 LEFT</td>
<td>13</td>
<td>I-GL4627</td>
<td>26</td>
</tr>
<tr>
<td>3</td>
<td>I-GL4609 RIGHT</td>
<td>14</td>
<td>I-GL4699</td>
<td>27</td>
</tr>
<tr>
<td>5</td>
<td>I-GL4621</td>
<td>15</td>
<td>I-GL4678</td>
<td>28</td>
</tr>
<tr>
<td>6</td>
<td>I-GL4615</td>
<td>18</td>
<td>I-GL4642</td>
<td>29</td>
</tr>
<tr>
<td>7</td>
<td>I-GL4672</td>
<td>19</td>
<td>I-GL4639</td>
<td>30</td>
</tr>
<tr>
<td>8</td>
<td>I-GL4675</td>
<td>20</td>
<td>I-GL4645</td>
<td>31</td>
</tr>
<tr>
<td>9</td>
<td>I-GL4618</td>
<td>21</td>
<td>I-GL4666</td>
<td>32</td>
</tr>
<tr>
<td>10</td>
<td>I-GL4630</td>
<td>22</td>
<td>I-GL4669</td>
<td>33</td>
</tr>
<tr>
<td>11</td>
<td>I-GL4633</td>
<td>23</td>
<td>I-GL4660</td>
<td>34</td>
</tr>
<tr>
<td></td>
<td></td>
<td>24</td>
<td>I-GL4663</td>
<td>35</td>
</tr>
</tbody>
</table>